Computer Architecture

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Lecture 19: Multiprocessing

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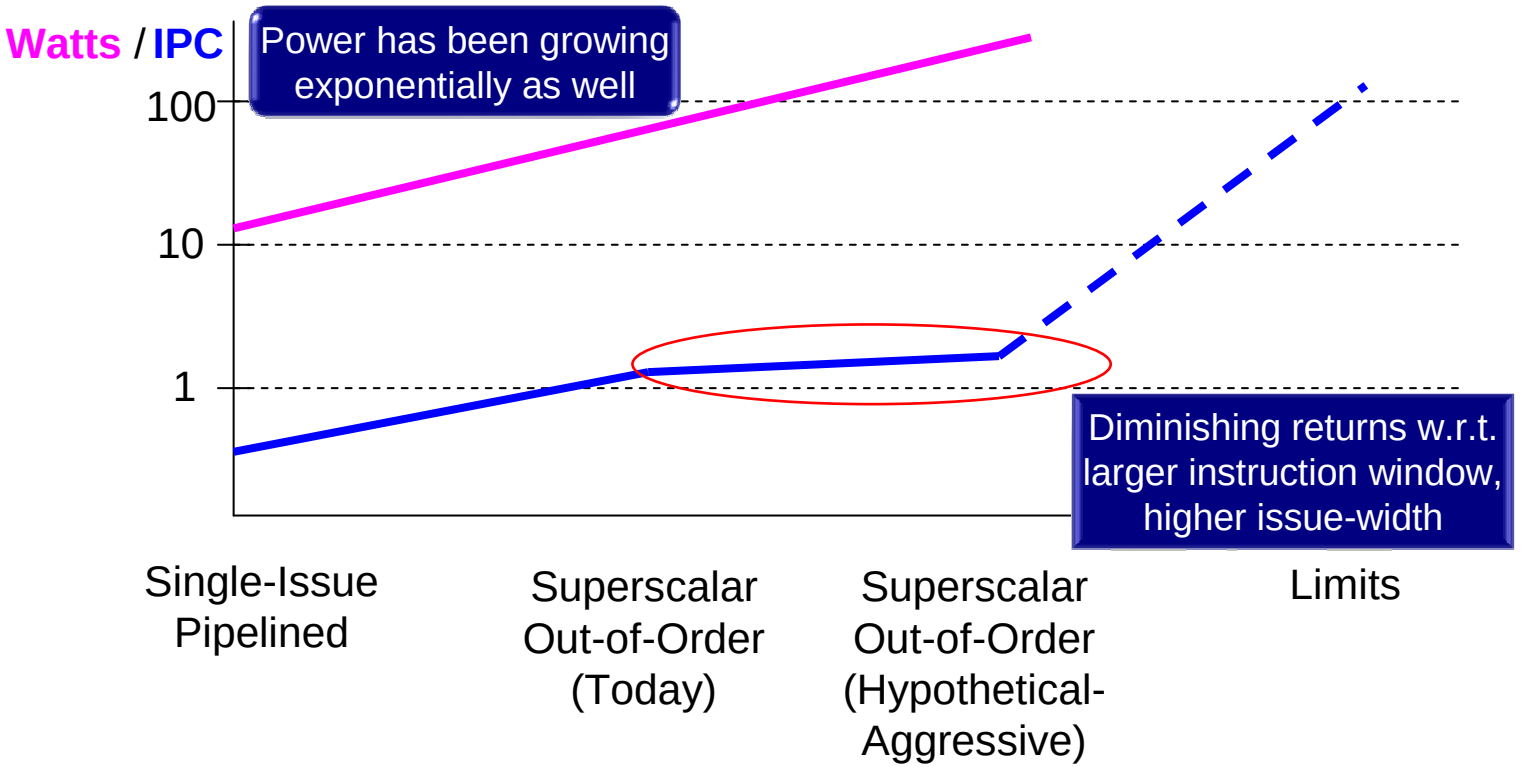
[Slides adapted from CSE 502 Stony Brook University]

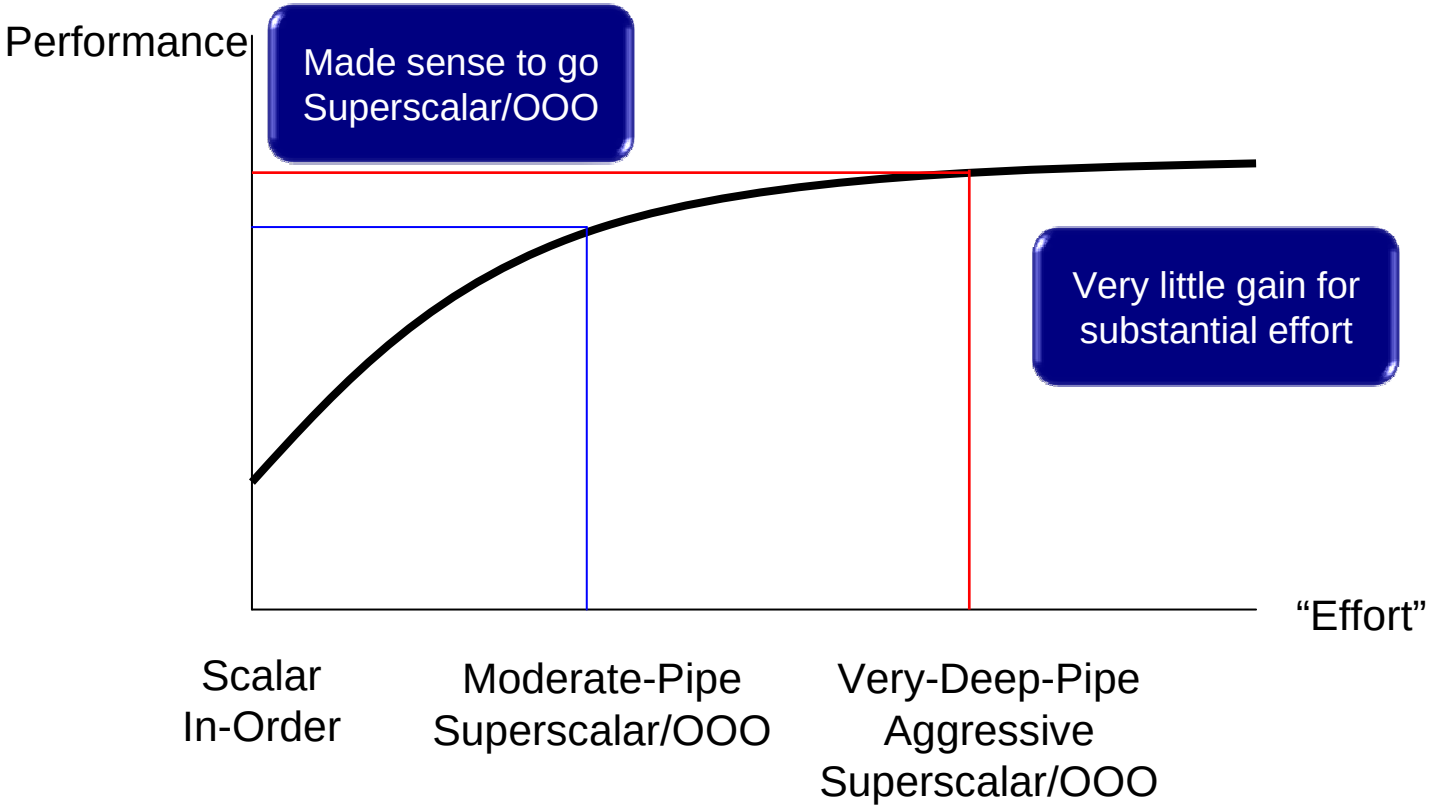
Getting More Performance

- Keep pushing IPC and/or frequenecy
  - Design complexity (time to market)
  - Cooling (cost)
  - Power delivery (cost)
  - …
- Possible, but too costly

Bridging the Gap



Higher Complexity not Worth Effort



User Visible/Invisible

- All performance gains up to this point were “free”
  - No user intervention required (beyond buying new chip)
    - Recompilation/rewriting could provide even more benefit
  - Higher frequency & higher IPC
  - Same ISA, different micro-architecture
- Multiprocessing pushes parallelism above ISA
  - Coarse grained parallelism
    - Provide multiple processing elements
  - User (or developer) responsible for finding parallelism
    - User decides how to use resources

Sources of (Coarse) Parallelism

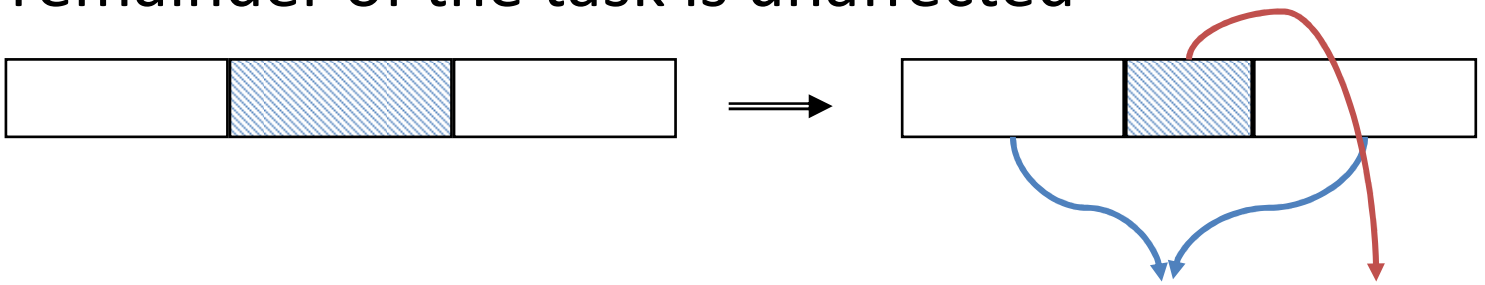
- Different applications
  - MP3 player in background while you work in Office
  - Other background tasks: OS/kernel, virus check, etc…
  - Piped applications
    - gunzip -c foo.gz | grep bar | perl some-script.pl
- Threads within the same application
  - Java (scheduling, GC, etc...)
  - Explicitly coded multi-threading
    - pthreads, MPI, etc…

Encountering Amdahl's Law

- Speedup due to enhancement E is

$$\text{Speedup w/ E} = \frac{\text{Exec time w/o E}}{\text{Exec time w/ E}}$$

- Suppose that enhancement E accelerates a fraction F (F <1) of the task by a factor S (S>1) and the remainder of the task is unaffected



$$\text{ExTime w/ E} = \text{ExTime w/o E} \times ((1\text{-}F) + F/S)$$

$$\text{Speedup w/ E} = 1 / ((1\text{-}F) + F/S)$$

Examples: Amdahl's Law

Speedup w/ E = 1 / ((1-F) + F/S)

- Consider an enhancement which runs 20 times faster but which is only usable 25% of the time.

  Speedup w/ E = 1/(.75 + .25/20) = 1.31

- What if its usable only 15% of the time?

  Speedup w/ E = 1/(.85 + .15/20) = 1.17

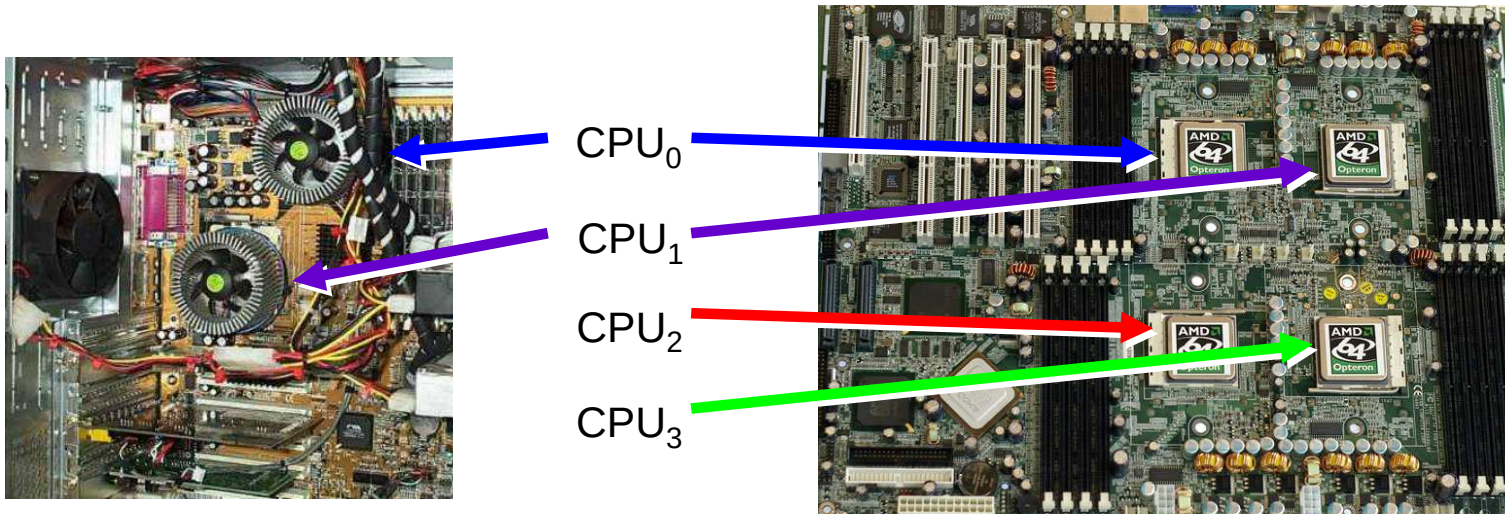
- Amdahl's Law tells us that to achieve linear speedup with 100 processors, none of the original computation can be scalar!
- To get a speedup of 99 from 100 processors, the percentage of the original program that could be scalar would have to be 0.01% or less

Flynn's Classification Scheme

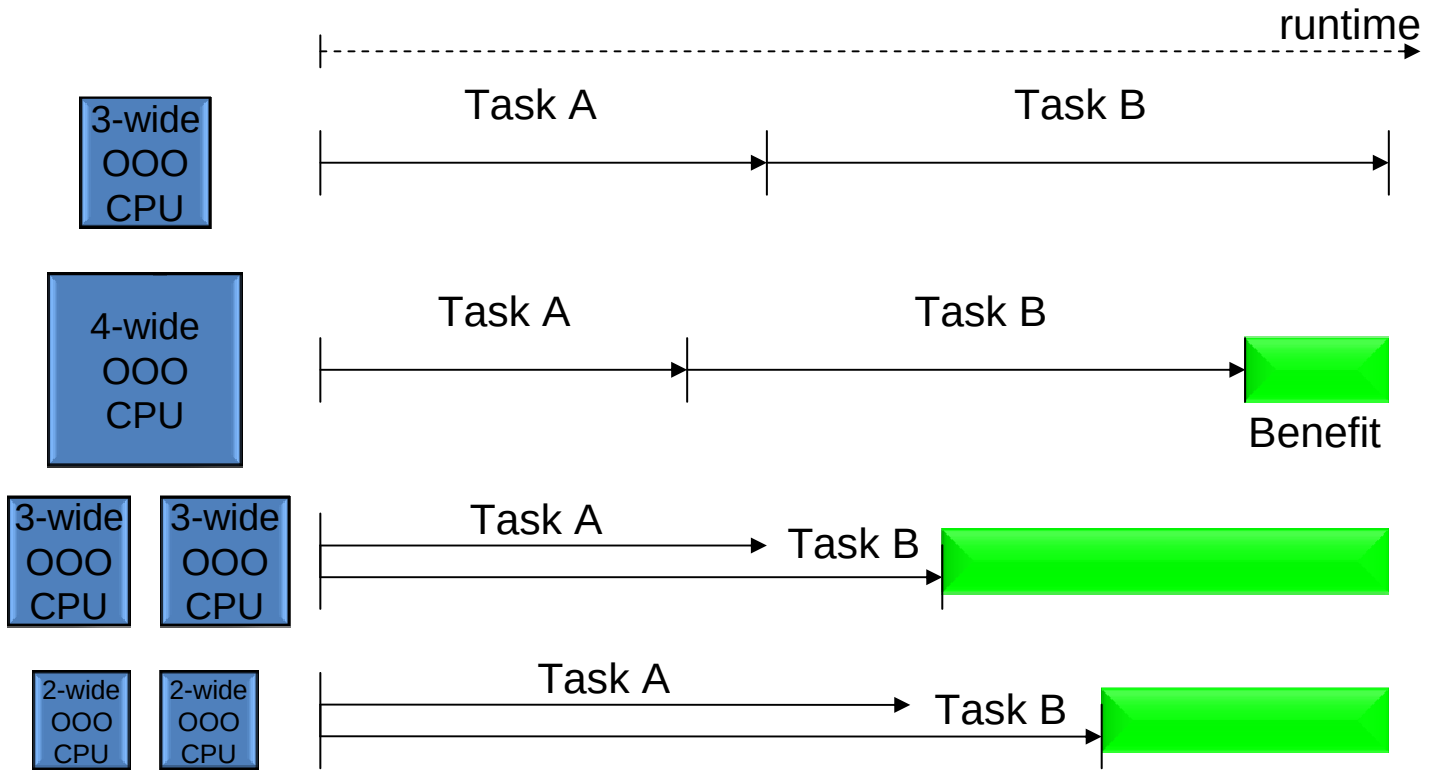
- SISD – single instruction, single data stream
  - aka uniprocessor - what we have been talking about all semester
- SIMD – single instruction, multiple data streams
  - single control unit broadcasting operations to multiple datapaths
- MISD – multiple instruction, single data stream
  - no such machine
- MIMD – multiple instructions, multiple data streams
  - aka multiprocessors, multicomputers (SMPs, clusters)

SMP Machines

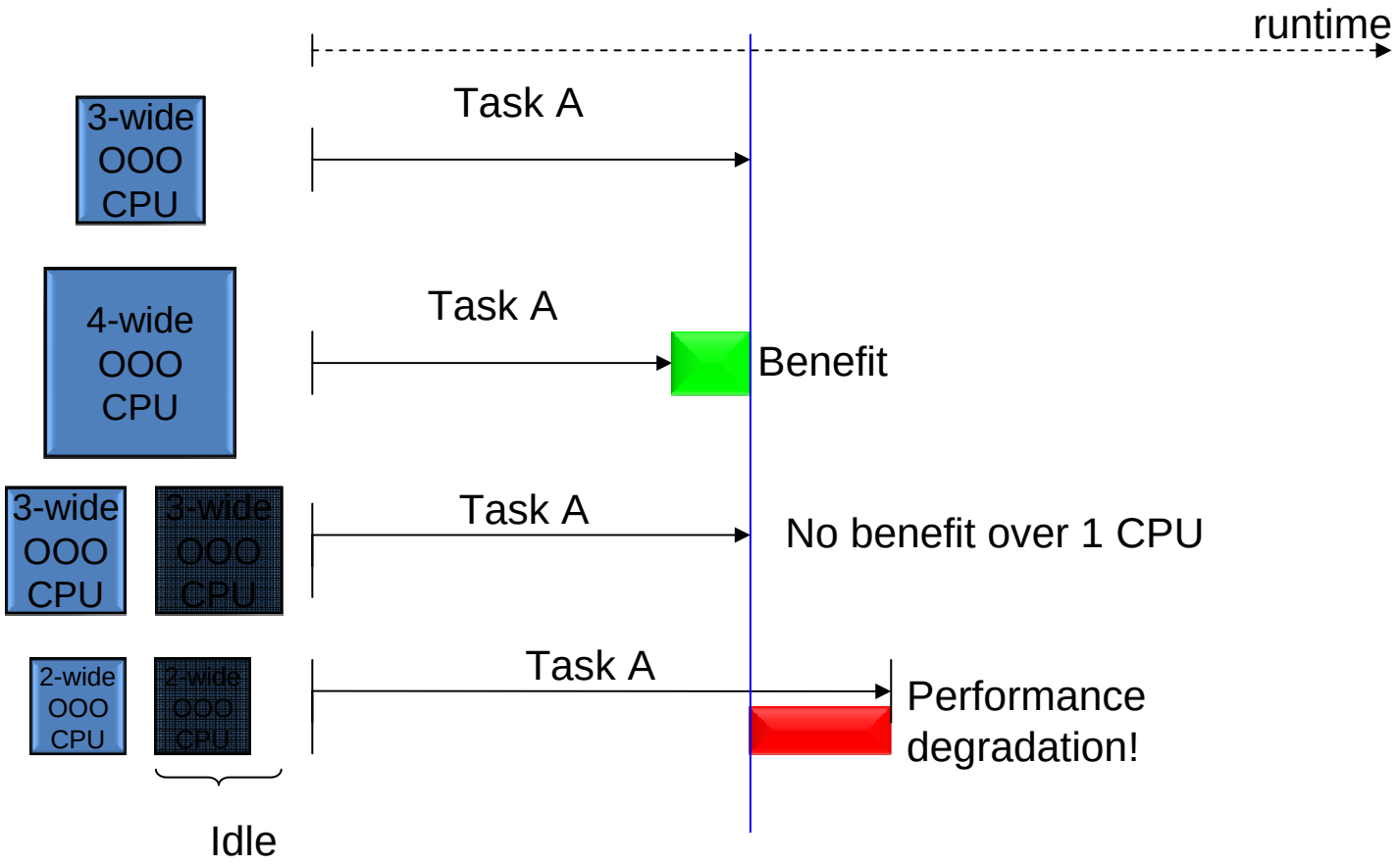
- *SMP* = Symmetric Multi-Processing
  - Symmetric = All CPUs have “equal” access to memory
- OS sees multiple CPUs
  - Runs one process (or thread) on each CPU



Multiprocessing Workload Benefits

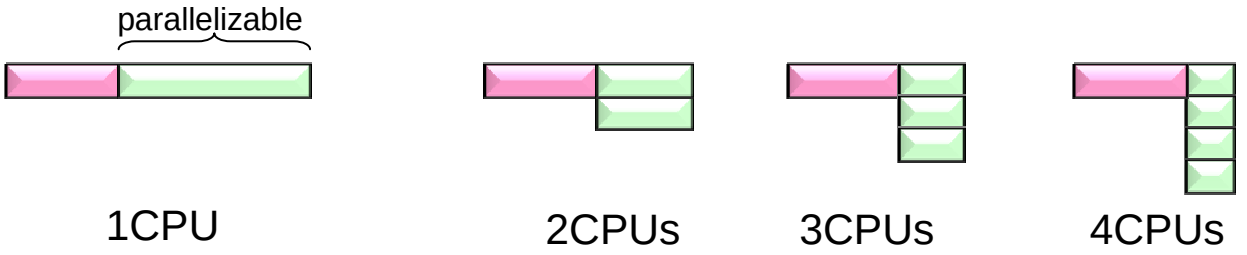


… If Only One Task Available



Benefit of Multiprocessing Depends on Workload

- Limited number of parallel tasks to run
  - Adding more CPUs than tasks provides zero benefit
- For parallel code, Amdahl's law curbs speedup

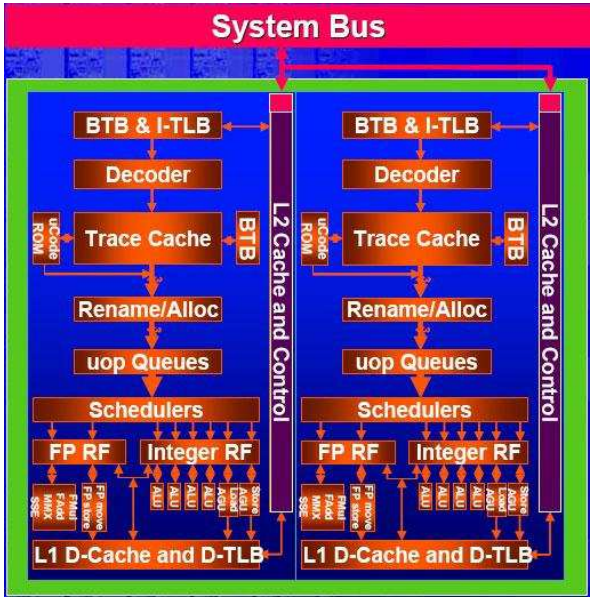


Hardware Modifications for SMP

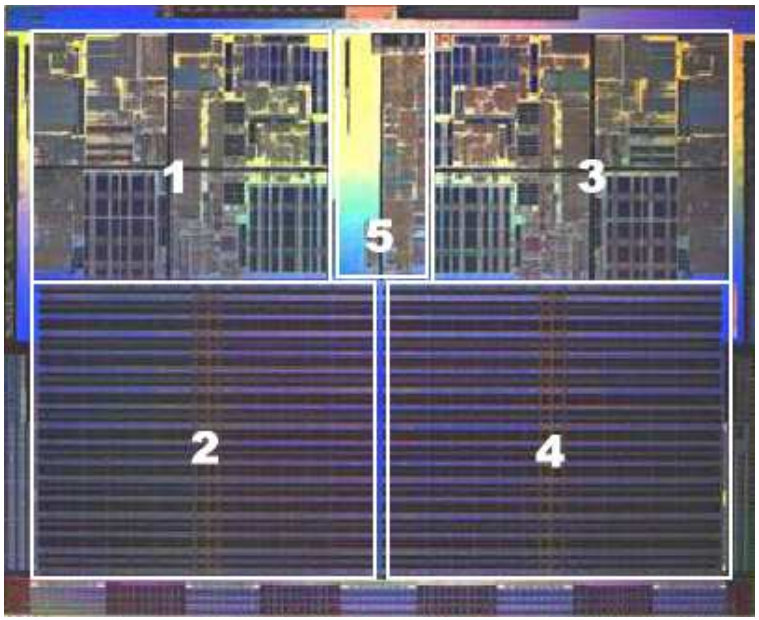
- Processor
  - Memory interface
- Motherboard
  - Multiple sockets (one per CPU)
  - Datapaths between CPUs and memory
- Other
  - Case: larger (bigger motherboard, better airflow)
  - Power: bigger power supply for N CPUs
  - Cooling: more fans to remove N CPUs worth of heat

Chip-Multiprocessing (*CMP*)

- Simple SMP on the same chip
  - CPUs now called “cores” by hardware designers
  - OS designers still call these “CPUs”



Intel “Smithfield” Block Diagram

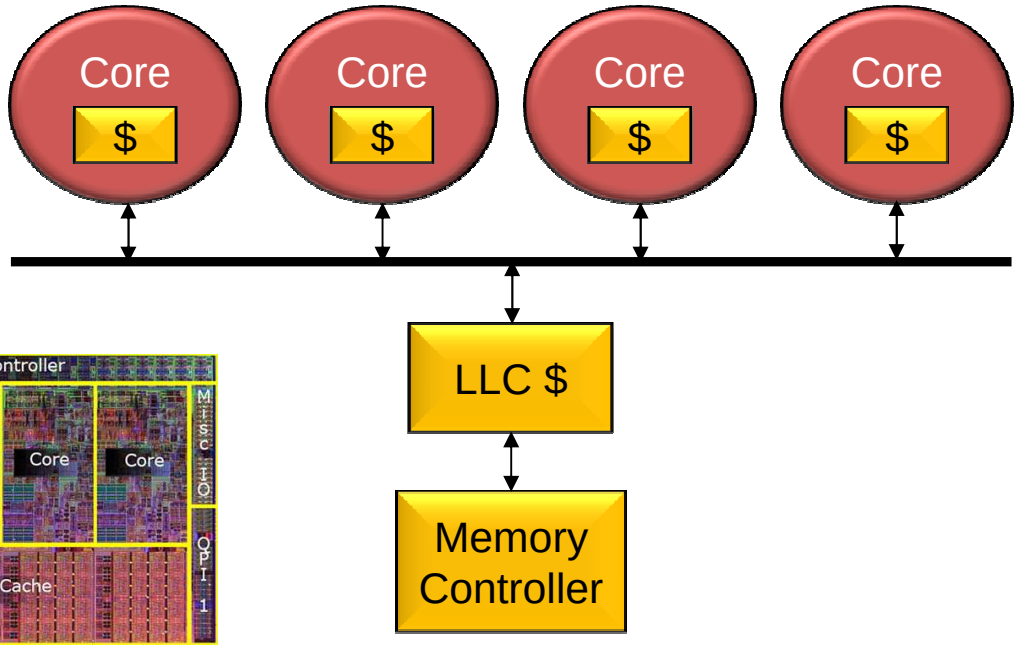


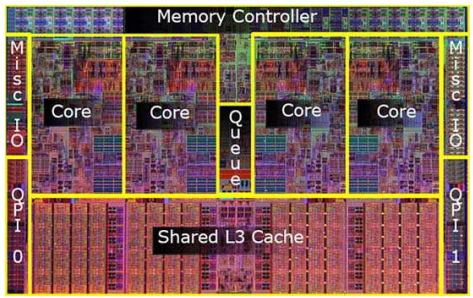
AMD Dual-Core Athlon FX

On-chip Interconnects (1/5)

- Today, (Core+L1+L2) = "*core*"
  - (L3+I/O+Memory) = "*uncore*"
- How to interconnect multiple "core"s to "uncore"?

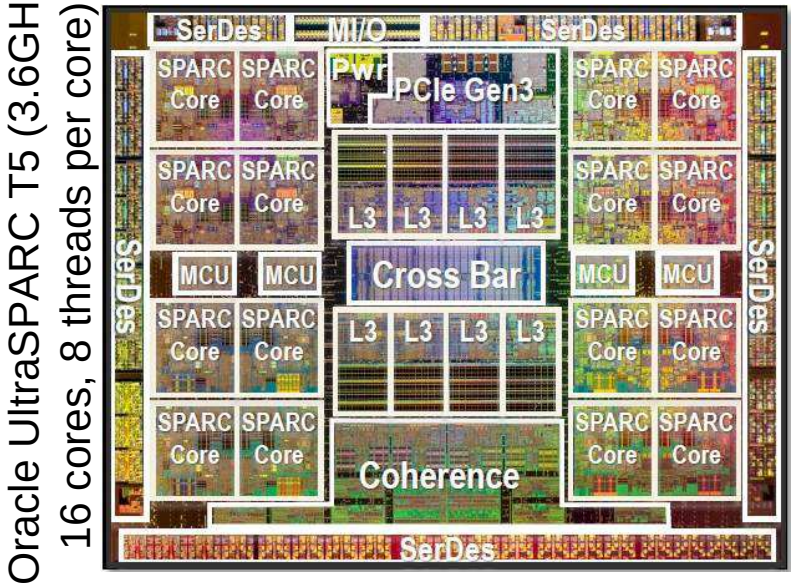
- Possible topologies
  - *Bus*
  - Crossbar
  - Ring
  - Mesh
  - Torus



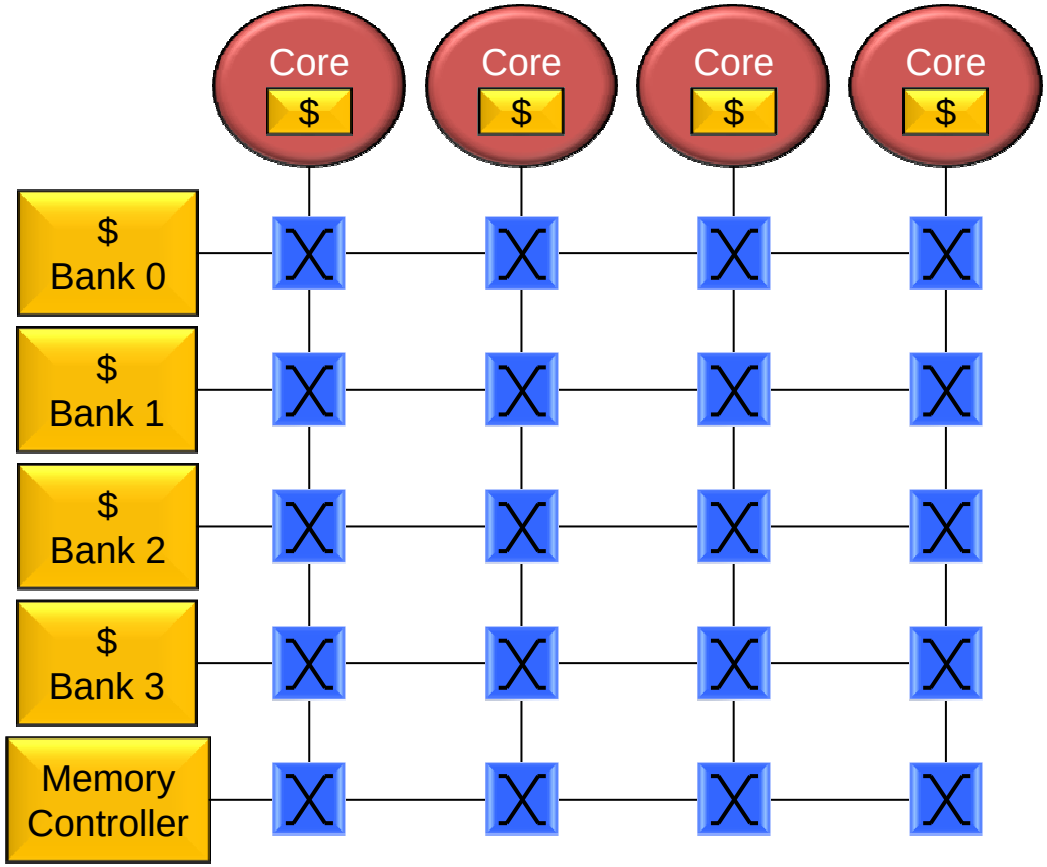


On-chip Interconnects (2/5)

- Possible topologies
  - Bus
  - *Crossbar*
  - Ring
  - Mesh
  - Torus

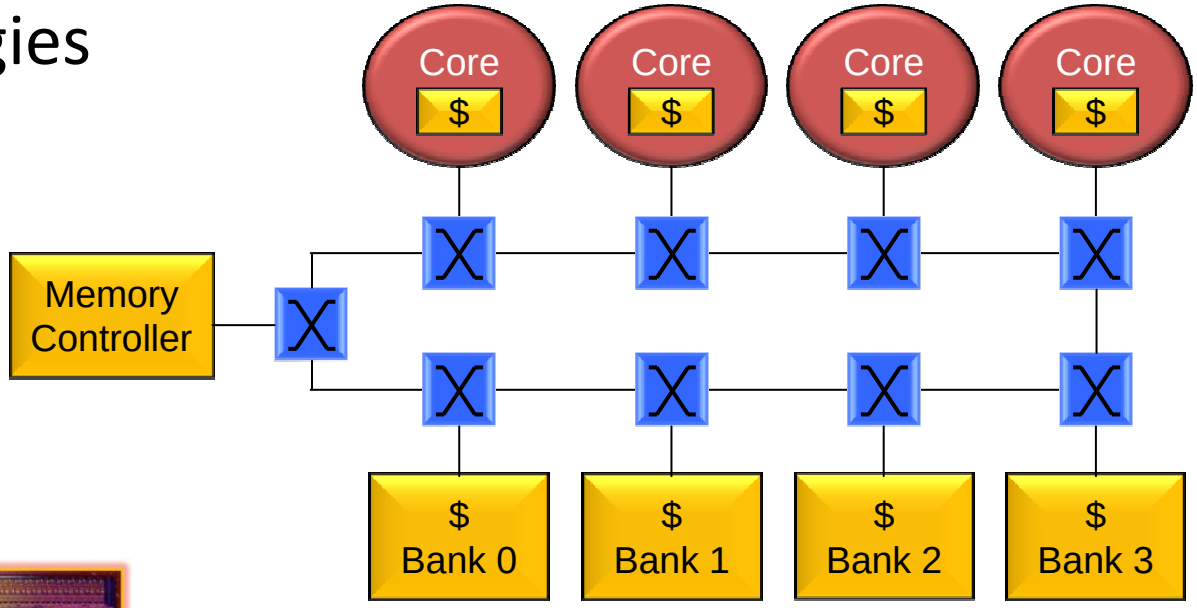


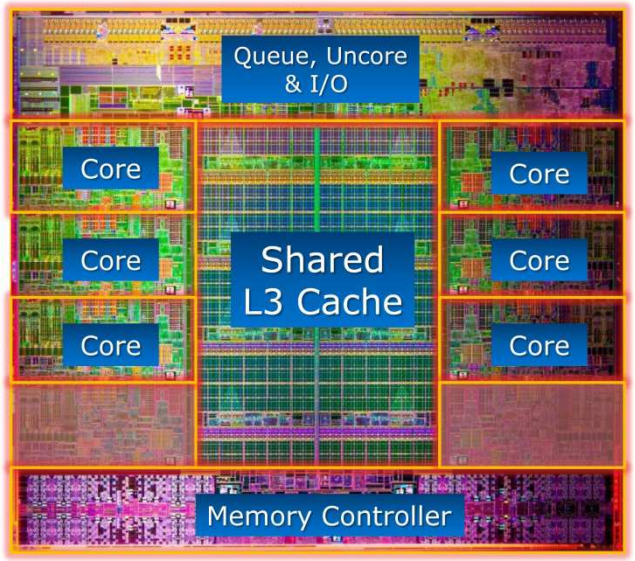
Oracle UltraSPARC T5 (3.6GHz, 16 cores, 8 threads per core)



On-chip Interconnects (3/5)

- Possible topologies
  - Bus
  - Crossbar
  - *Ring*
  - Mesh
  - Torus





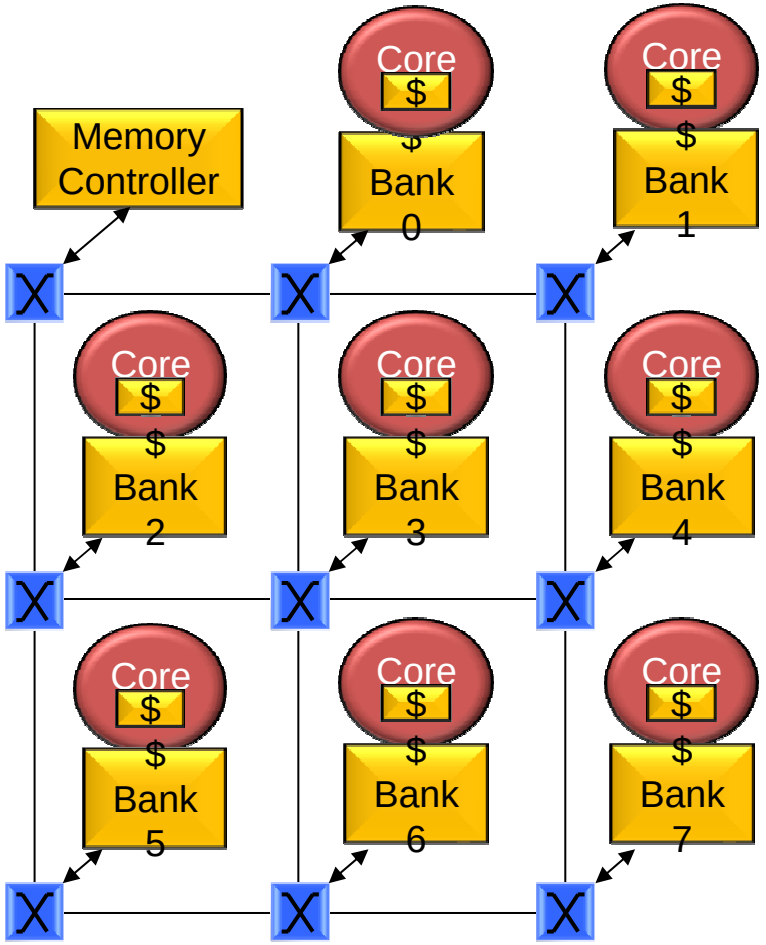
Intel Sandy Bridge (3.5GHz, 6 cores, 2 threads per core)

- 3 ports per switch
- Simple and cheap
- Can be bi-directional to reduce latency

On-chip Interconnects (4/5)

- Possible topologies
  - Bus
  - Crossbar
  - Ring
  - *Mesh*
  - Torus

Tilera Tile64 (866MHz, 64 cores)



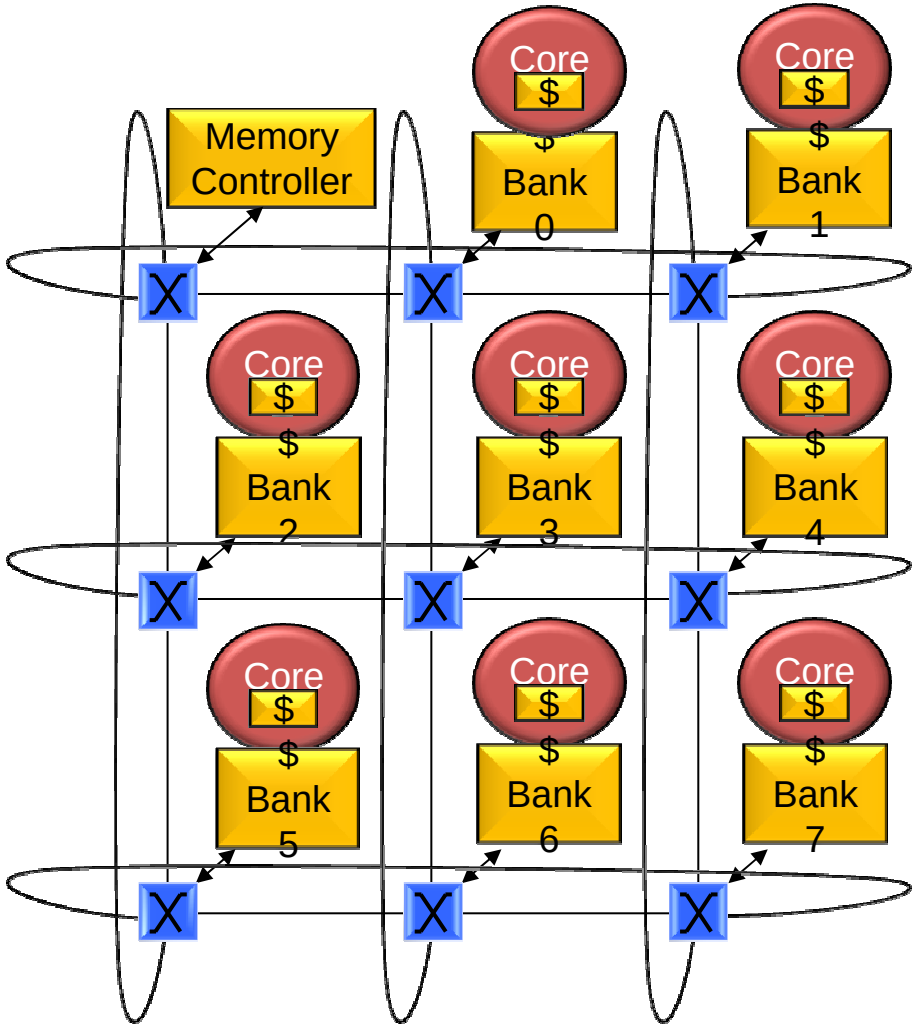
- Up to 5 ports per switch

Tiled organization combines core and cache

On-chip Interconnects (5/5)

- Possible topologies
  - Bus
  - Crossbar
  - Ring
  - Mesh
  - *Torus*

- 5 ports per switch
- Can be “folded” to avoid long links



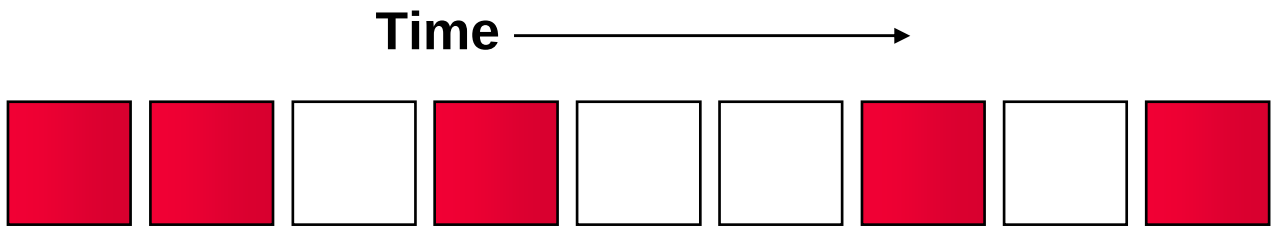
Benefits of CMP

- Cheaper than multi-chip SMP
  - All/most interface logic integrated on chip
    - Fewer chips
    - Single CPU socket
    - Single interface to memory
  - Less power than multi-chip SMP
    - Communication on die uses less power than chip to chip
- Efficiency
  - Use for transistors instead of wider/more aggressive OoO
  - Potentially better use of hardware resources

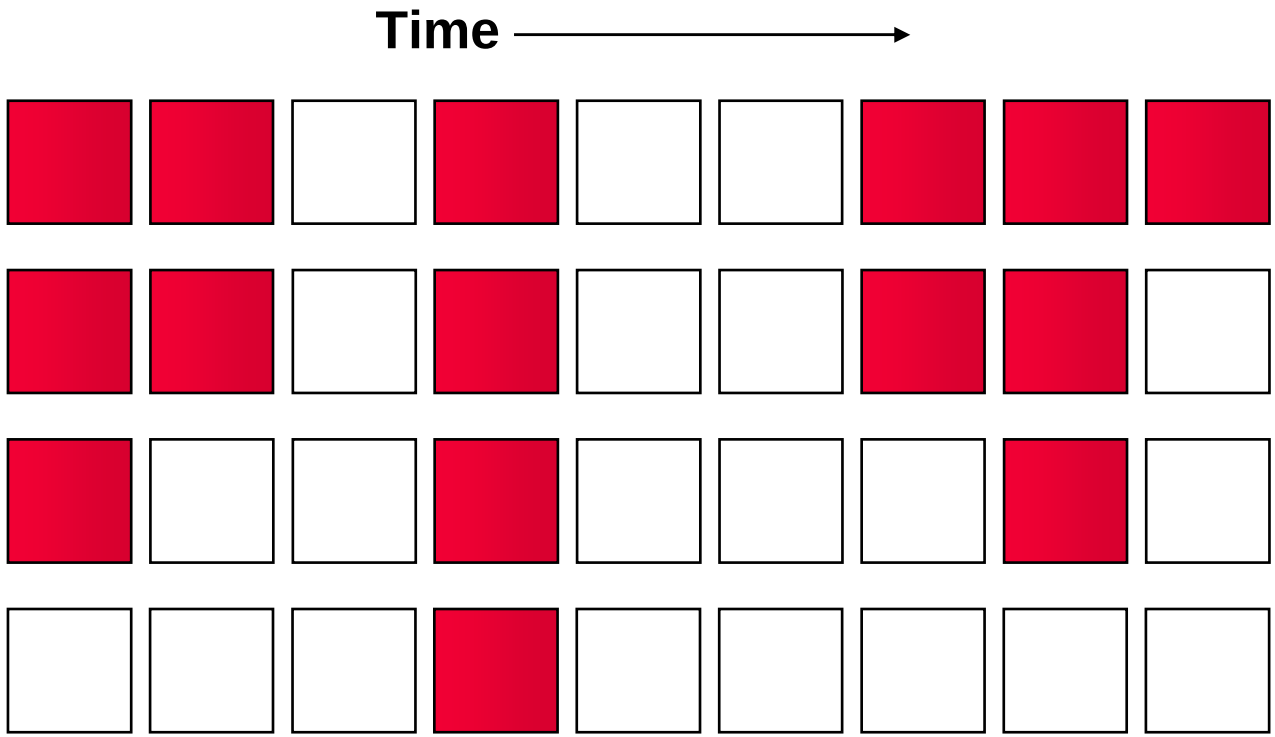
Multi-Threading

- Uni-Processor: 4-6 wide, lucky if you get 1-2 IPC
  - Poor utilization of transistors
- SMP: 2-4 CPUs, but need independent threads
  - Poor utilization as well (if limited tasks)
- *{Coarse-Grained,Fine-Grained,Simultaneous}-MT*
  - Use single large uni-processor as a multi-processor
    - Core provide multiple hardware contexts (threads)
      - Per-thread PC
      - Per-thread ARF (or map table)
  - Each core appears as multiple CPUs
    - OS designers still call these “CPUs”

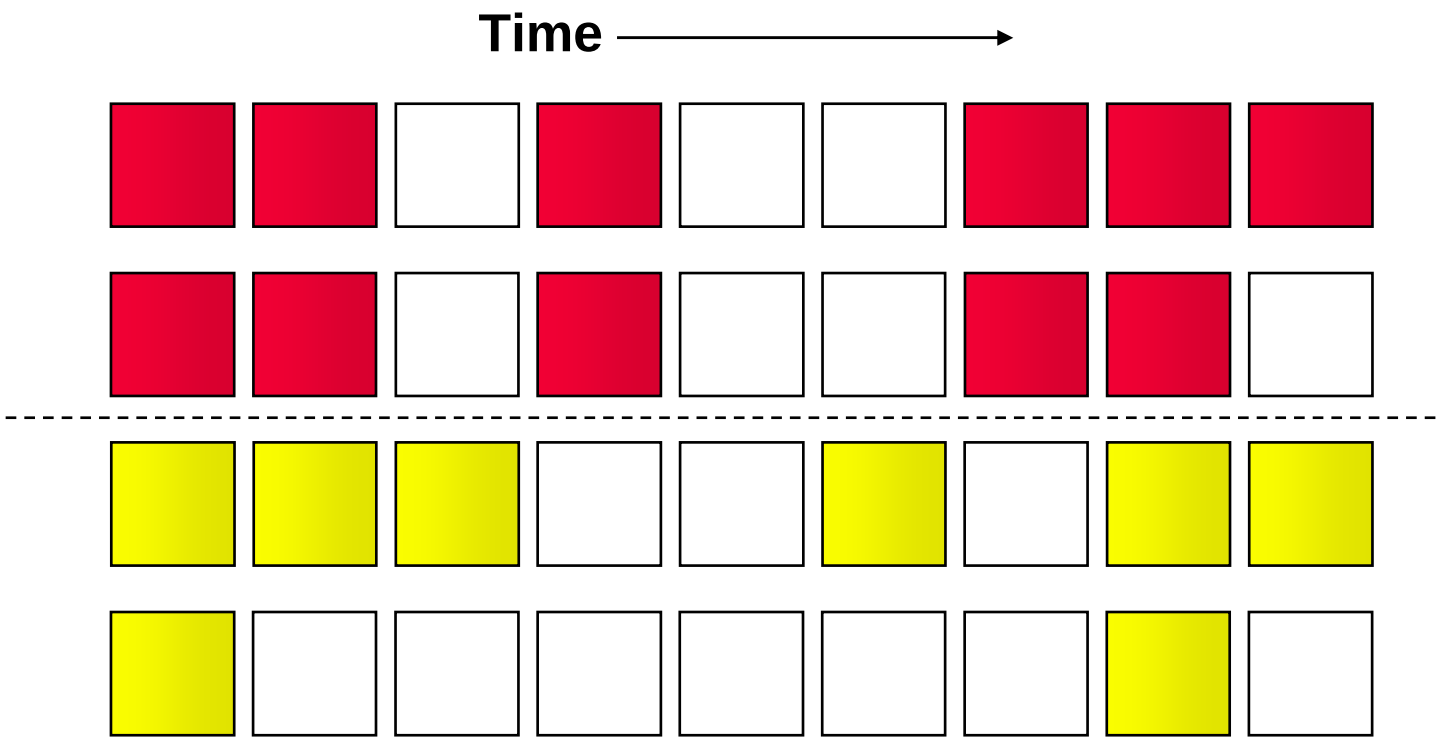
Scalar Pipeline



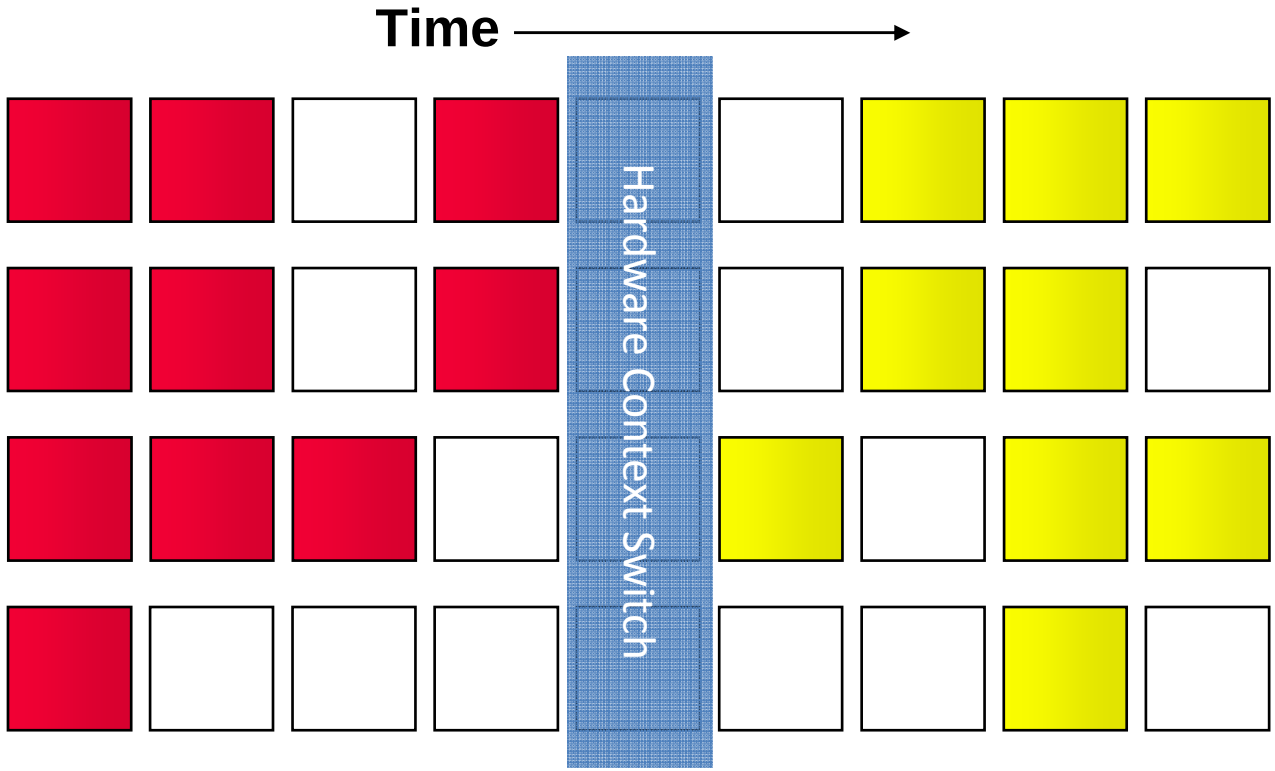
Superscalar Pipeline



Chip Multiprocessing (CMP)



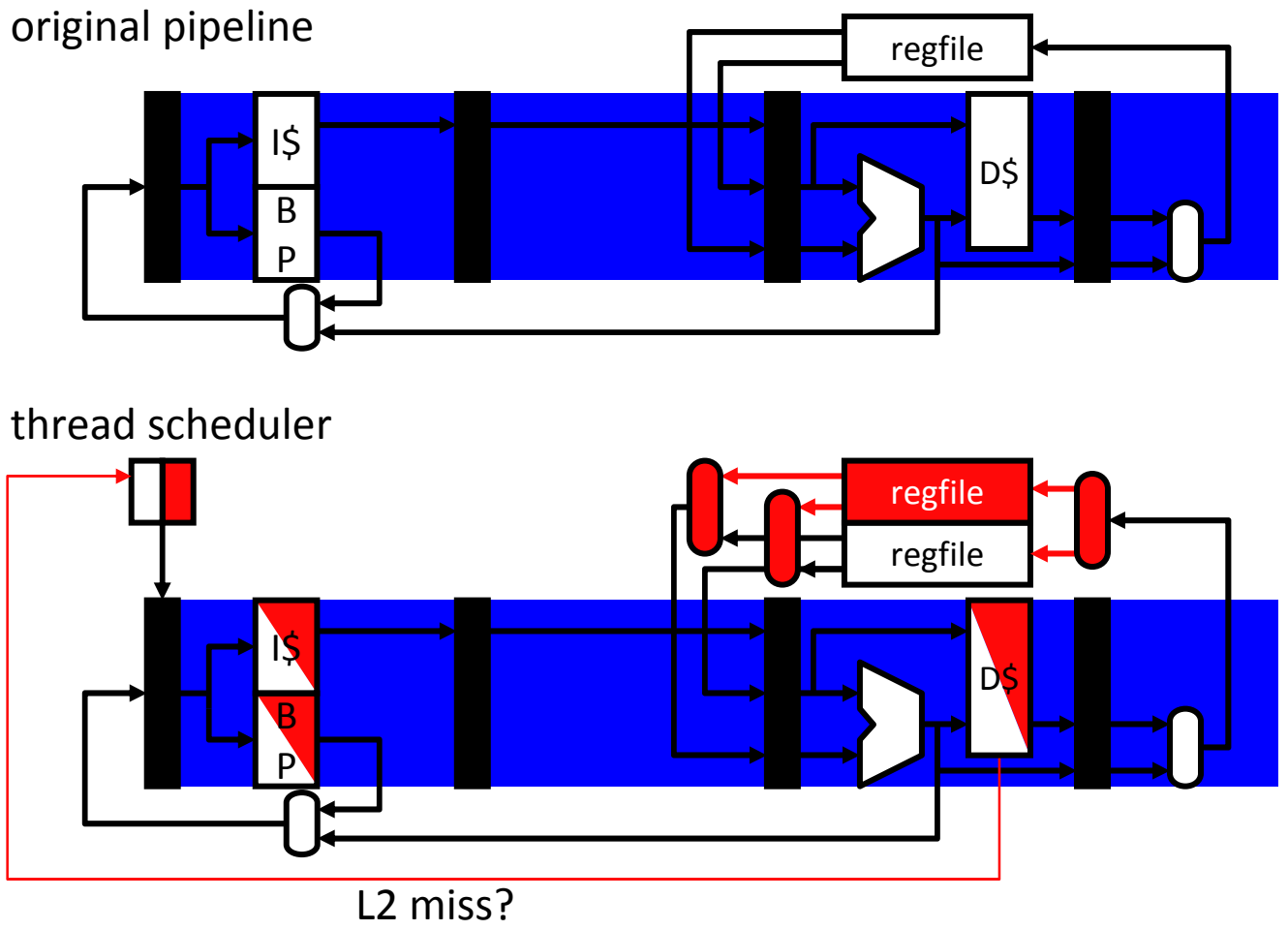
Coarse-Grained Multithreading (1/3)



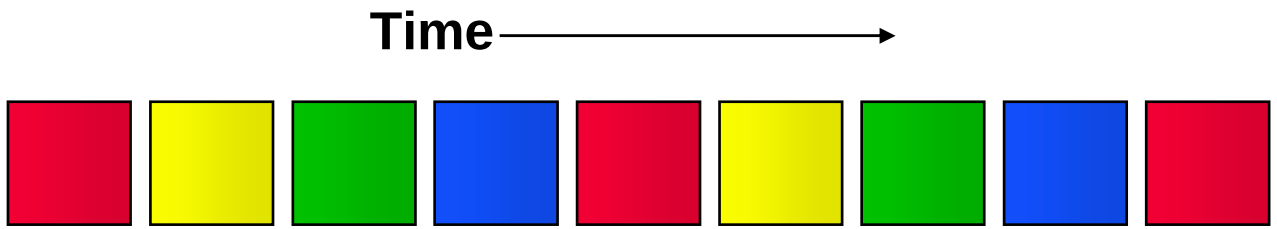
Coarse-Grained Multithreading (2/3)

+ Sacrifices a little single thread performance
– Tolerates only long latencies (e.g., L2 misses)
- Thread scheduling policy
  - Designate a “preferred” thread (e.g., thread A)
  - Switch to thread B on thread A L2 miss
  - Switch back to A when A L2 miss returns
- Pipeline partitioning
  - None, flush on switch
  - Can’t tolerate latencies shorter than twice pipeline depth
  - Need short in-order pipeline for good performance

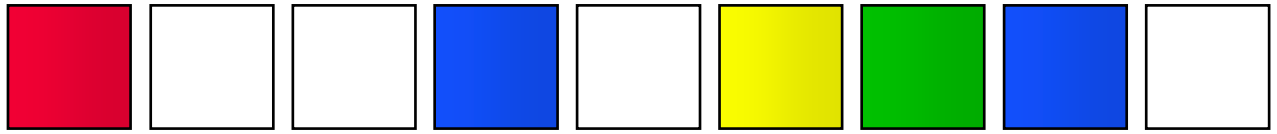
Coarse-Grained Multithreading (3/3)



Fine-Grained Multithreading (1/3)



Saturated workload → Lots of threads



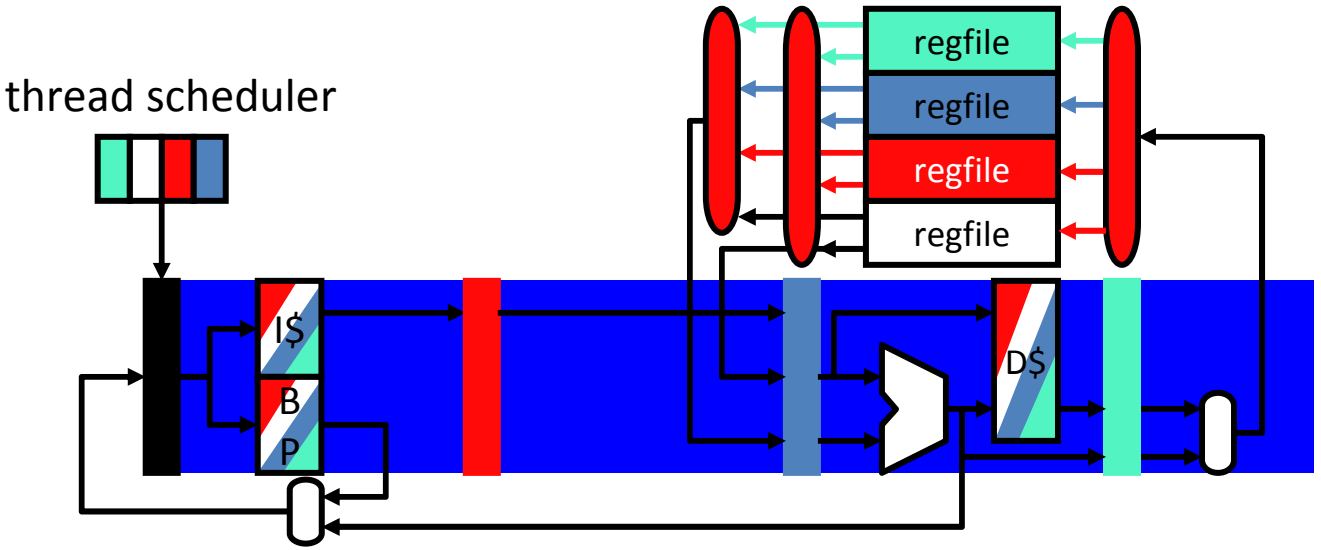
Unsaturated workload → Lots of stalls

Fine-Grained Multithreading (2/3)

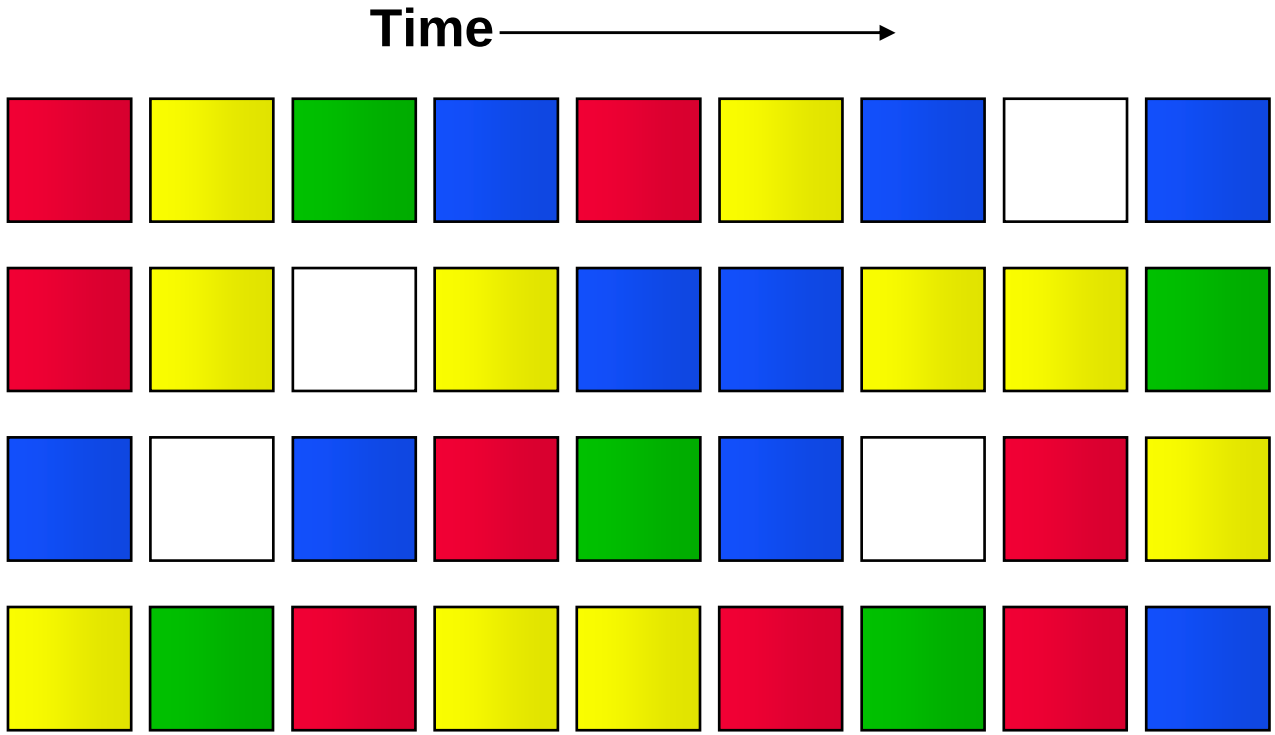
- – Sacrifices significant single-thread performance
- \+ Tolerates everything
  - \+ L2 misses
  - \+ Mispredicted branches
  - \+ etc...
- • Thread scheduling policy
  - – Switch threads often (e.g., every cycle)
  - – Use round-robin policy, skip threads with long-latency ops
- • Pipeline partitioning
  - – Dynamic, no flushing
  - – Length of pipeline doesn’t matter

Fine-Grained Multithreading (3/3)

- (Many) more threads
- Multiple threads in pipeline at once



Simultaneous Multithreading (1/3)



Simultaneous Multithreading (2/3)

+ Tolerates all latencies

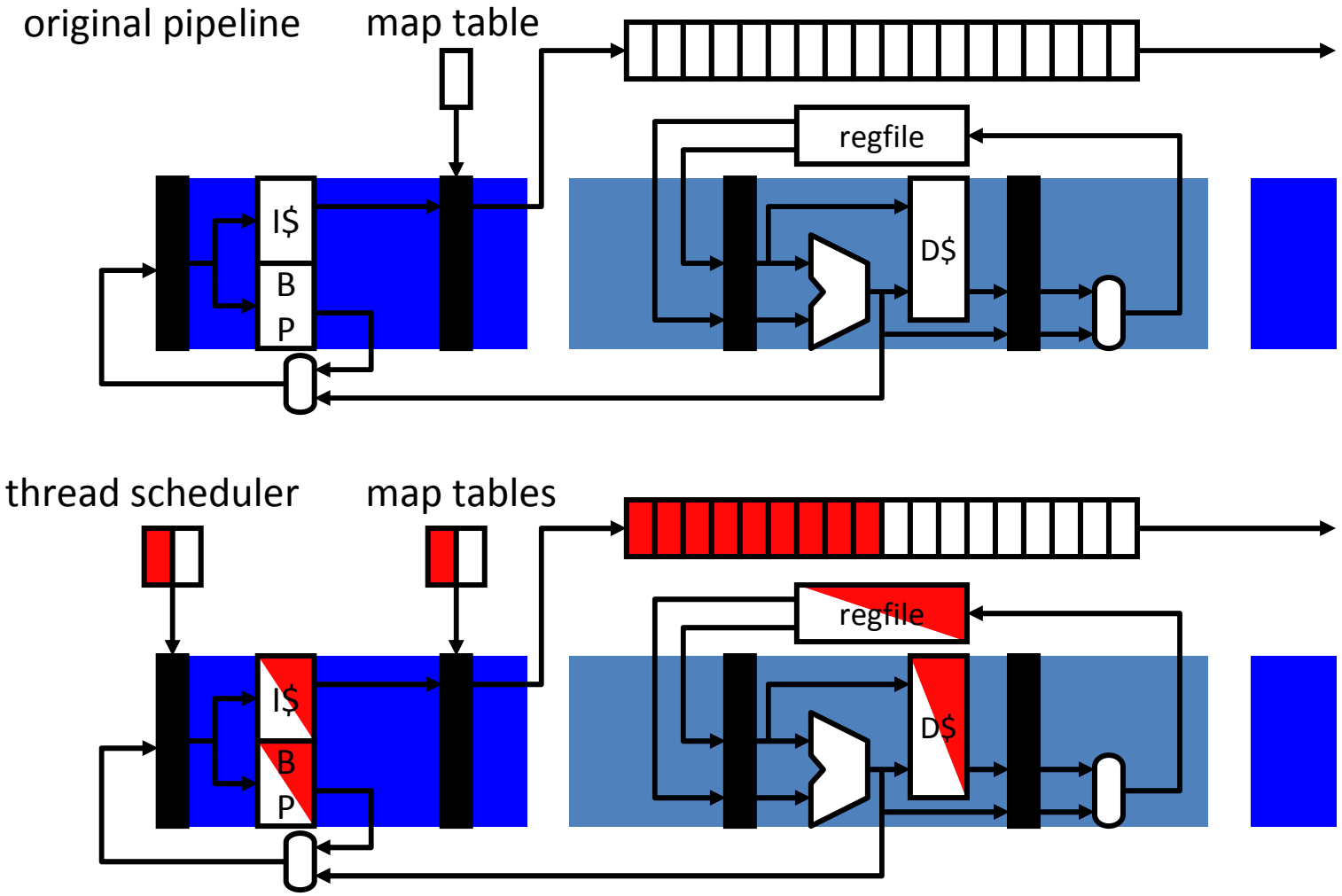
± Sacrifices some single thread performance

– Thread scheduling policy
  - Round-robin (like Fine-Grained MT)

– Pipeline partitioning
  - Dynamic

– Examples
  – Pentium4 (*hyper-threading*): 5-way issue, 2 threads
  – Alpha 21464: 8-way issue, 4 threads (canceled)

Simultaneous Multithreading (3/3)



Latency vs. Throughput

- MT trades (single-thread) latency for throughput
  - Sharing processor degrades latency of individual threads
  - But improves aggregate latency of both threads
  - Improves utilization
- Example
  - Thread A: individual latency=10s, latency with thread B=15s
  - Thread B: individual latency=20s, latency with thread A=25s
  - Sequential latency (first A then B or vice versa): 30s
  - Parallel latency (A and B simultaneously): 25s
  - MT slows each thread by 5s
  - But improves total latency by 5s

CMP vs. MT

- If you wanted to run multiple threads would you build a…
  - Chip multiprocessor (CMP): multiple separate pipelines?
  - A multithreaded processor (MT): a single larger pipeline?
- Both will get you throughput on multiple threads
  - CMP will be simpler, possibly faster clock
  - SMT will get you better performance (IPC) on a single thread
    - SMT is basically an ILP engine that converts TLP to ILP
    - CMP is mainly a TLP engine
- Do both (CMP of MTs), Example: Sun UltraSPARC T1
  - 8 processors, each with 4-threads (fine-grained threading)
  - 1Ghz clock, in-order, short pipeline
  - Designed for power-efficient “throughput computing”

Combining MP Techniques (1/2)

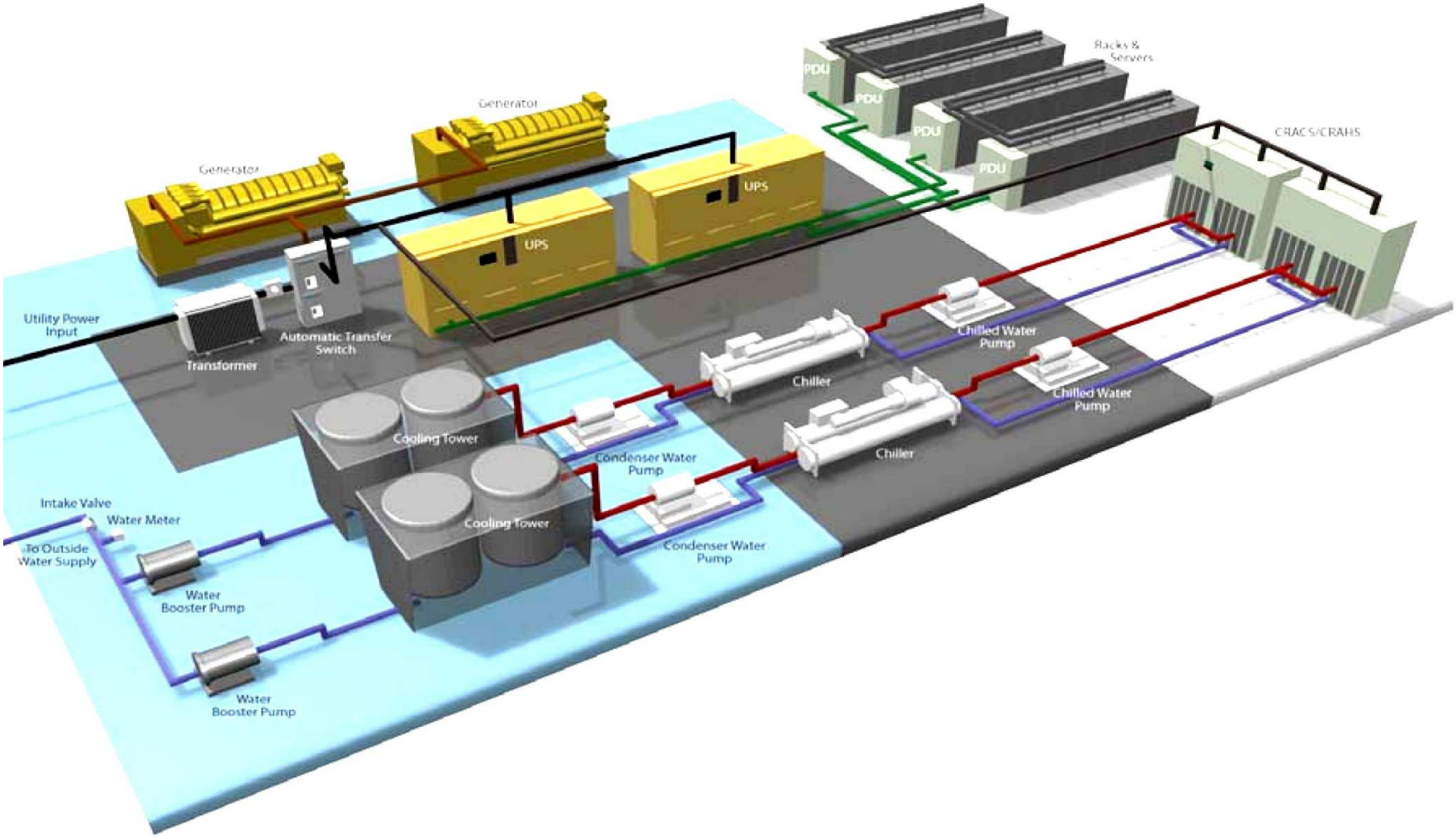
- System can have SMP, CMP, and SMT at the same time
- Example machine with 32 threads
  - Use 2-socket SMP motherboard with two chips
  - Each chip with an 8-core CMP
  - Where each core is 2-way SMT
- Makes life difficult for the OS scheduler
  - OS needs to know which CPUs are…
    - Real physical processor (SMP): highest independent performance
    - Cores in same chip: fast core-to-core comm., but shared resources
    - Threads in same core: competing for resources
  - Distinct apps. scheduled on different CPUs
  - Cooperative apps. (e.g., pthreads) scheduled on same core
  - Use SMT as last choice (or don't use for some apps.)

Combining MP Techniques (2/2)

Scalability Beyond the Machine

Server Racks

Datacenters (1/2)



Datacenters (2/2)