

Supplemental Material for A-Optimal Projection for Image Representation

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1 PROOF OF THEOREM 3.1

By using Woodbury matrix identity, Eq. (14) can be rewritten as follows:

$$\begin{aligned} & \text{Tr}\left((A^T \tilde{X} \tilde{X}^T A + \lambda_2 I)^{-1}\right) \\ &= \text{Tr}\left(\frac{1}{\lambda_2} I - \frac{1}{\lambda_2} A^T \tilde{X} \left(I + \frac{1}{\lambda_2} \tilde{X}^T A A^T \tilde{X}\right)^{-1} \tilde{X}^T A\right) \\ &= \frac{k}{\lambda_2} - \frac{1}{\lambda_2} \text{Tr}\left(A^T \tilde{X} (\lambda_2 I + \tilde{X}^T A A^T \tilde{X})^{-1} \tilde{X}^T A\right) \end{aligned}$$

Noticing that $\text{Tr}(AB) = \text{Tr}(BA)$, we have:

$$\begin{aligned} & \text{Tr}\left((A^T \tilde{X} \tilde{X}^T A + \lambda_2 I)^{-1}\right) \\ &= \frac{k}{\lambda_2} - \frac{1}{\lambda_2} \text{Tr}\left((\lambda_2 I + \tilde{X}^T A A^T \tilde{X})^{-1} \tilde{X}^T A A^T \tilde{X}\right) \\ &= \frac{k}{\lambda_2} - \frac{1}{\lambda_2} \text{Tr}\left((\lambda_2 I + \tilde{X}^T A A^T \tilde{X})^{-1} \right. \\ & \quad \left. (\tilde{X}^T A A^T \tilde{X} + \lambda_2 I - \lambda_2 I)\right) \\ &= \frac{k}{\lambda_2} - \frac{1}{\lambda_2} \text{Tr}\left(I - \lambda_2 (\lambda_2 I + \tilde{X}^T A A^T \tilde{X})^{-1}\right) \\ &= \frac{k-n}{\lambda_2} + \text{Tr}\left((\lambda_2 I + \tilde{X}^T A A^T \tilde{X})^{-1}\right) \end{aligned}$$

This completes the proof.

2 PROOF OF THEOREM 4.1

Let $H = g(M) = \lambda I + \tilde{X}^T M \tilde{X}$. It is easy to see that g is an affine function of M . Therefore, g is convex. Let $f(H) = \text{Tr}(H^{-1})$ which is also convex [1]. Thus, $f \circ g(M) = \text{Tr}\left((\lambda I + \tilde{X}^T M \tilde{X})^{-1}\right)$ is convex. This completes the proof.

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3 PROOF OF THEOREM 4.2

Let M_a^* be the optimal solution of problem (17), and (P^*, M_b^*) be the optimal solutions of problem (18). Then $M_a^* = M_b^*$ is a sufficient condition for Theorem 4.2. We define

$$f(M) = (\lambda I + \tilde{X}^T M \tilde{X})^{-1}.$$

Assume $M_a^* \neq M_b^*$. Since M_a^* minimizes the problem (17), we have

$$\text{Tr}f(M_a^*) < \text{Tr}f(M_b^*).$$

Note that (P^*, M_b^*) satisfies the conditions in problem (18), so we have

$$\begin{aligned} & P^* \succeq_{\mathbb{S}_n^+} f(M_b^*) \\ \Leftrightarrow & P^* - f(M_b^*) \in \mathbb{S}_n^+ \\ \Leftrightarrow & \text{Tr}P^* > \text{Tr}f(M_b^*) \end{aligned}$$

It is clear that $(f(M_b^*), M_a^*)$ satisfies the conditions in problem (18). Thus, for problem (18), $(f(M_b^*), M_a^*)$ is more optimal than P^*, M_b^* , which contradicts our assumption. Therefore, we have $M_a^* = M_b^*$.

4 PROOF OF THEOREM 4.3

Let $\phi = \|I - A^T \tilde{X} B\|^2 + \lambda \|B\|^2$. Thus, we have

$$\begin{aligned} \phi &= \|I - A^T \tilde{X} B\|^2 + \lambda \|B\|^2 \\ &= \text{Tr}\left((I - A^T \tilde{X} B)(I - A^T \tilde{X} B)^T\right) + \lambda \text{Tr}(BB^T) \\ &= k - 2\text{Tr}(A^T \tilde{X} B) + \text{Tr}(A^T \tilde{X} B B^T \tilde{X}^T A) + \lambda \text{Tr}(BB^T) \end{aligned} \quad (1)$$

Noticing that

$$\begin{aligned} \frac{\partial \text{Tr}(A^T \tilde{X} B)}{\partial B^T} &= A^T \tilde{X}, \\ \frac{\partial \text{Tr}(A^T \tilde{X} B B^T \tilde{X}^T A)}{\partial B^T} &= 2B^T \tilde{X}^T A A^T \tilde{X}, \end{aligned}$$

and

$$\frac{\partial \text{Tr}(BB^T)}{\partial B^T} = 2B^T.$$

By requiring the gradient of ϕ with respect to B^T vanish, we have

$$\begin{aligned} \frac{\partial \phi}{\partial B^T} &= 0 \\ \Rightarrow B^T \tilde{X}^T A A^T \tilde{X} + B^T - A^T \tilde{X} &= 0 \\ \Rightarrow B &= (\tilde{X}^T A A^T \tilde{X} + \lambda I)^{-1} \tilde{X}^T A. \end{aligned} \quad (2)$$

Substituting Eq. (2) into Eq. (1) and noticing that $\text{Tr}(AB) = \text{Tr}(BA)$, we have

$$\begin{aligned} &\text{Tr}(A^T \tilde{X} B) \\ &= \text{Tr}\left(A^T \tilde{X} (\tilde{X}^T A A^T \tilde{X} + \lambda I)^{-1} \tilde{X}^T A\right) \\ &= \text{Tr}\left((\tilde{X}^T A A^T \tilde{X} + \lambda I)^{-1} \tilde{X}^T A A^T \tilde{X}\right) \\ &= \text{Tr}\left((\tilde{X}^T A A^T \tilde{X} + \lambda I)^{-1} (\tilde{X}^T A A^T \tilde{X} + \lambda I - \lambda I)\right) \\ &= n - \lambda \text{Tr}\left((\tilde{X}^T A A^T \tilde{X} + \lambda I)^{-1}\right), \end{aligned} \quad (3)$$

and,

$$\begin{aligned} &\text{Tr}(A^T \tilde{X} B B^T \tilde{X}^T A) + \lambda \text{Tr}(B B^T) \\ &= \text{Tr}(B B^T \tilde{X}^T A A^T \tilde{X}) + \lambda \text{Tr}(B B^T) \\ &= \text{Tr}\left(B B^T (\tilde{X}^T A A^T \tilde{X} + \lambda I)\right) \\ &= \text{Tr}\left((\tilde{X}^T A A^T \tilde{X} + \lambda I)^{-1} \tilde{X}^T A A^T \tilde{X} (\tilde{X}^T A A^T \tilde{X} + \lambda I)^{-1} \right. \\ &\quad \left. (\tilde{X}^T A A^T \tilde{X} + \lambda I)\right) \\ &= \text{Tr}\left((\tilde{X}^T A A^T \tilde{X} + \lambda I)^{-1} \tilde{X}^T A A^T \tilde{X}\right) \\ &= n - \lambda \text{Tr}\left((\tilde{X}^T A A^T \tilde{X} + \lambda I)^{-1}\right). \end{aligned} \quad (4)$$

Finally, we have

$$\phi = k - n + \lambda \text{Tr}\left((\tilde{X}^T A A^T \tilde{X} + \lambda I)^{-1}\right). \quad (5)$$

Thus, the optimal A is given by solving the following problem:

$$\min_A \text{Tr}\left((\tilde{X}^T A A^T \tilde{X} + \lambda I)^{-1}\right). \quad (6)$$

This completes the proof.

REFERENCES

- [1] S. Boyd and L. Vandenberghe. *Convex Optimization*. Cambridge University Press, 2004.